

2 LK1 ~ LK6: Unassigned

3 P1 ~ P16: 1 Byte data

P1 Decelerated speed in rapid traverse (%)

P2 Max. approach length in thread cutting
(thread lead x N)

I = 0.1 times

P3 Error rate in thread cutting (%)

P8 Turret index position selection

0: X = max. OD + Parameter data (X)

Z = Z end face + Parameter data (Z)

1: X = zero point

Z = Z end face + Parameter data (X)

2: X = max. OD + Parameter data (Z)

Z = zero point

3: X = zero point

Z = zero point

P9 Simple automatic tool compensation

0: Disable

1: Count up of number of machined works

2: Tool service hours

P10 Spear tool index

0: Disable

1: Count up of number of machined works

2: Tool service hours

3: Wear of tool, exceeding max. limit

P11 Automatic "handle" interrupt magnification

X 0 ~ X 100 Need Switch

P16 Inch system

Others Unassigned

4 P17 ~ P32: 2 Byte data

P17 Undercut height for grinding (1 μ unit, in radius)

P18 Undercut width for grinding (1 μ unit, in radius)

P19 Reduction rate of depth of cut in bar turning
(rough cut) (%)

P23 Finishing allowance in thread cutting
(1 μ unit, in diameter)

P24 Clearance in thread cutting (1 μ unit, in diameter)

P25 Step amount in grooving (1 μ unit, in radius)

P26 Tolerance of infeed amount in drilling
(1 μ unit, in radius)

P27 Step amount in drilling (1 μ unit, in radius)

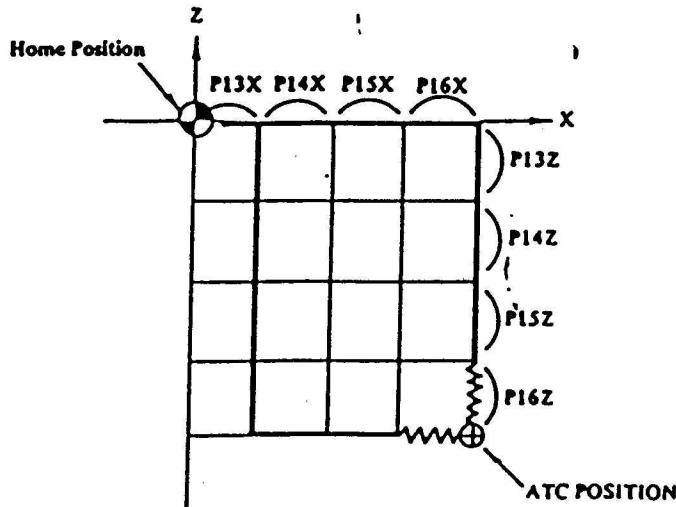
P28	Slotting overlap
P29	Measured stroke
P30	Tool nose measuring sensor diameter
P31	Speed at measurement
P32	Speed at measurement approach
Others	Unassigned

5 P33 ~ P48: 4 Byte data

P33	Tool nose measuring sensor position (X)
P34	Tool nose measuring sensor position (Z)
P35	Tool change position (index) clear (X)
P36	Tool change position (index) clear (Z)
P40	Dwell when thread cutting starts
P41	Dowel time for grooving
P42	Infeed clamp amount in drilling (1 μunit, in radius)
P47	Automatic "handle" interrupt clamp value (X)
P48	Automatic "handle" interrupt clamp value (Z)
Others	Unassigned

6 PX1 ~ PX16: 4 Byte data (X/Z)

PX1	Air cut clearance X/Z (1 unit, in diameter)
PX3	Air cut clearance in grooving X/Z (1 unit, in diameter)
PX13 (X/Z)	ATC position (index) setting 1
PX14 (X/Z)	ATC position (index) setting 2
PX15 (X/Z)	ATC position (index) setting 3
PX16 (X/Z)	ATC position (index) setting 4
(Others are not in use.)	



Parameter No. 2 Screen

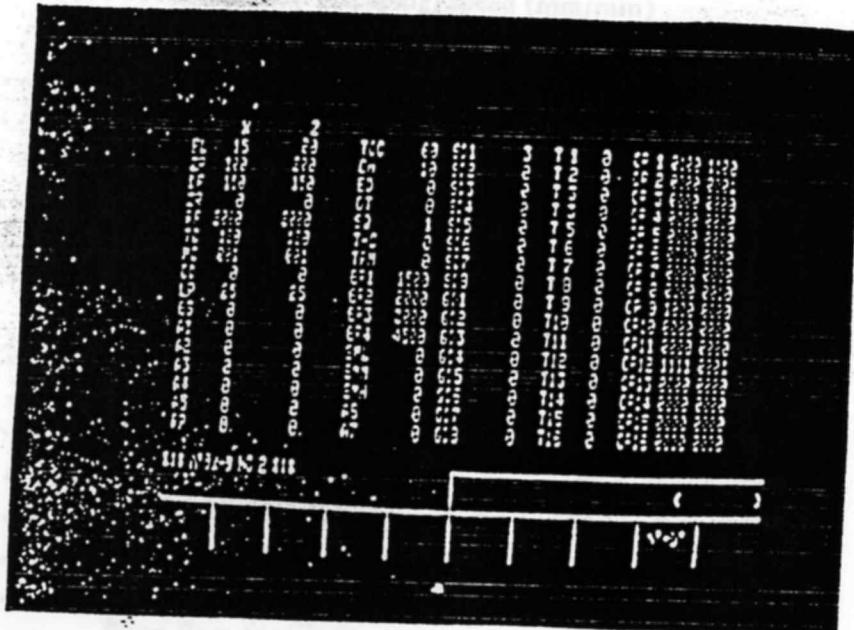
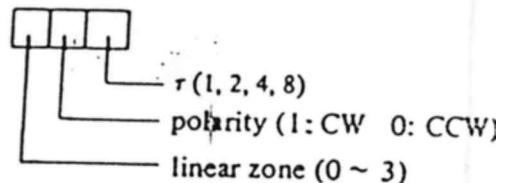
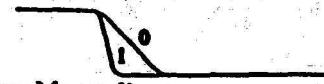


Fig. 9-3.

- BL X/Z Backlash amount (in diameter, 0 ~ 16383)
- ZP X/Z Zero point shift amount
(in diameter, 0 ~ 16383)
- DF X/Z Creep speed in zero return (0 ~ 500 mm/min.)
- ZR X/Z Direction of zero point
(0: positive, 1: negative)
- RF X/Z Rapid traverse speed (0 ~ 20,000 mm/min.)
- TC X/Z Time constant of rapid traverse
(0 ~ 500 msec.)
- MC X/Z Servo constant



- OD X/Z Time constant reduction rate in overtravelling (0 ~ 63%)
LP X/Z Position loop gain
AI ATC approach (creeping) speed (mm/min)
RP X/Z Coordinates of reference point
TCC Time constant of cutting feed (1 ~ 500 msec)
CH Chamfering width (0 ~ 40)
 $I = 0.1 \times$ thread lead
ED Smoothing zero detection remaining distance
(0 ~ 2000 μ)
OT Axis stop method in case of overtravelling
(1: servo off, 0: linear-deceleration)

SQ Machine sequence constant (See YL Sequence Manual)
TRM Switchover of chamfering constant
Chamfering length
GR1 Gear 1, spindle max. speed
GR2 Gear 2, spindle max. speed
GR3 Gear 3, spindle max. speed
GR4 Gear 4, spindle max. speed
A7 Feed Rate for CMT:
SD1 System parameter
SD2 Spindle gearing step setting
SD3 Setting of number of tools on tool post (Lear Turnet)
QDI ~ QD8 Machine sequence data (See YL Sequence Manual)
T1 ~ T8 Machine sequence timer (0 ~ 255 I = 0.1 sec) (See YL Sequence Manual)
T9 ~ TI6 Machine sequence timer (0 ~ 255 I = 1 sec.) (See YL Sequence Manual)
OP1 ~ OP16 System parameter